

Key data	ENX 22 EMT	
Multi-turn: max. no. of turns	65 536	
Multi-turn: resolution (bits)	16	
Single-turn: steps per turns	131072	
Single-turn: resolution (bits)	17	
Encoder length L1	mm 22.75	
Ambient temperature	°C -40 +105	
Weight	g 25	

Selection criteria	ENX 22 EMT	
Multi-turn detection		
Detection of speed and rotation direction		
Speed and position control		
Compact and robust design		
High resolution		
Economical		
Leonomical		

■ suitable ▲ suitable to a limited extent ● not suitable

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Specifications		ENX 22 EMT		
Supply voltage Vcc	V	5 ±0.5		
Typical current draw	mA	90		
Max. speed	rpm	12000		
Data encoding		Binary		
Min. clock frequency CLK (MHz)		BiSS-C: 0.1	SSI: 0.08	
Max. clock frequency CLK (MHz)		BiSS-C: 10	SSI:1	
Min. timeout (μs)		BiSS-C: 712.5	SSI: 6	
Setup time after Power On	S	Max. 0.1		
Moment of inertia of pulse disk	gmm²	≤ 1.55		
Plug manufacturer JST Plug type no. BM08B-NSHSS -TBT Matching connector type no. NSHR-08V-S		Pin 1: GND Pin 2: Do not connect Pin 3: Do not connect Pin 4: Data+ / SLO+ Pin 5: Data- / SLO- Pin 6: CLK- / MA- Pin 7: CLK+ / MA+ Pin 8 V <sub>cc</sub> Output signals: EIA st Output current per ch	andard RS422	8

Configuration	ENX 22 EMT	
Signal protocol	BiSS-C, SSI	

maxon modular system maxon EC motor EC-4pole 22 EC-4pole 30	Page Dim 257-258 259/261	ensions of standard configuration	M1:2 Additional information  1 The length shown here refers to the encoder. An additional intermediate plate is required for motor mounting. For more detailed information, see the combined dimensional drawing.  EC motors: The angle value 0 is calibrated to the commutation phase of coil 1 (equates to Hall signal 1 for motors with Hall sensors, block commutation), see p. 56.  Ordering information: For motors that cannot be configured online, the part numbers 711113 (BiSS-C) and 711112 (SSI) must be used when ordering.  You can find more information in the maxon online shop under Downloads.
		nnecting cable 300 mm for OS4 Aux Enc <mark>708590</mark>	xdrives.maxongroup.com